SCL Processing.nb

■ Processing APMP_Cal data from SCL Hong Kong

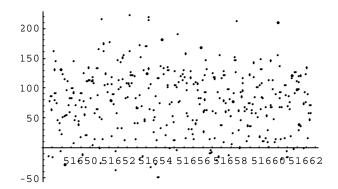
```
In[1]:= Off[General::spell1];
In[2]:= dataPath = "g:\\APMP_Cal\\";
```

■ Definitions

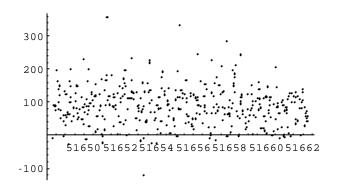
```
In[25]:= dataHost = ReadCCTF["host.scl.dat"];
          (*Host reported values:*)
          RepHostIntDly = 55;
            RepHostRefDly = 10;
           RepHostAntDly = 728;
          RepHostDly = RepHostIntDly + RepHostAntDly - RepHostRefDly;
          (*Host Receiver internal settings:*)
          RxHostIntDly = 55;
            RxHostRefDly = 10;
           RxHostAntDly = 728;
          RxHostDly = RxHostIntDly + RxHostAntDly - RxHostRefDly;
          HostCorrection = RepHostDly - RxHostDly;
          dataTrav = ReadCCTF["trav.scl.dat"];
          (*Host reported values:*)
          RepTravIntDly = 68;
            RepTravRefDly = 10;
           RepTravAntDly = 720;
          RepTravDly = RepTravIntDly + RepTravAntDly - RepTravRefDly;
          (*Travelling receiver internal settings:*)
          RxTravIntDly = 68;
            RxTravRefDly = 10;
           RxTravAntDly = 720;
          RxTravDly = RxTravIntDly + RxTravAntDly - RxTravRefDly;
          TravCorrection = RepTravDly - RxTravDly;
       > Read 382 tracks from g:\APMP_Cal\host.scl.dat
       > Read 346 tracks from g:\APMP_Cal\trav.scl.dat
In[45]:= << Graphics `Graphics`</pre>
```

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In[46]:= ListPlot[MakeXY[Map[DateValue, dataTrav], Map[RefGPS, dataTrav]]];



In[47]:= ListPlot[MakeXY[Map[DateValue, dataHost]], Map[RefGPS, dataHost]]];



```
In[48]:= dMerge = MergeCCTF[dataHost, dataTrav];
```

> First 382 tracks, second 346 tracks, matching 289 tracks

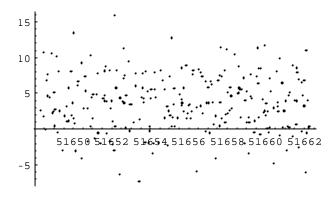
In[49]:= diffdataGPS =

Map[{DateValue[#1], RefSV[#1] - RefSV2[#1] - HostCorrection + TravCorrection,
 TrackLength[#1], TrackLength2[#1]} &, dMerge];

In[50]:= diffdataGPS = FilterTrackLength[diffdataGPS, 780];

256 common tracks out of 289 were of length greater than or equal to 780 seconds.

In[51]:= ListPlot[diffdataGPS, PlotRange -> All];



In[52]:= << Statistics`LinearRegression`</pre>

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```
In[53]:= regress = Regress[diffdataGPS, {1, x}, x];
         rtable = ANOVATable /. regress;
         ptable = ParameterTable /. regress;
         MJDFirst = First[dMerge][[3]];
         MJDLast = Last[dMerge][[3]];
         MJDMiddle = MJDFirst + (MJDFirst - MJDLast) / 2;
         intercept = ptable[[1, 1, 1]];
         SEintercept = ptable[[1, 1, 2]];
         slope = ptable[[1, 2, 1]];
         SEslope = ptable[[1, 2, 2]];
         rms = Sqrt[rtable[[1, 2, 3]]];
         MeanOffset = intercept + slope * MJDMiddle;
         Print["Summary"];
         Print[Length[dMerge], " common-view tracks were analysed between MJD ",
          MJDFirst, " and MJD ", MJDLast];
         Print["The mean offset (Host Rx - Travelling Rx) between the two receivers was ",
          MeanOffset, " ns, with an RMS deviation of ", rms, " ns."];
         Print["The slope of the line of best fit was ", slope * 1000,
           " ps/day, with a standard error of ", SEslope * 1000, " ps/day."];
       Summary
       289 common-view tracks were analysed between MJD 51648 and MJD 51662
       The mean offset (Host Rx - Travelling Rx) between the two receivers was
        3.97377 ns, with an RMS deviation of 3.90487 ns.
       The slope of the line of best fit was -21.5095
         ps/day, with a standard error of 60.0925 ps/day.
```