

■ Processing APMP_Cal data from NML Australia

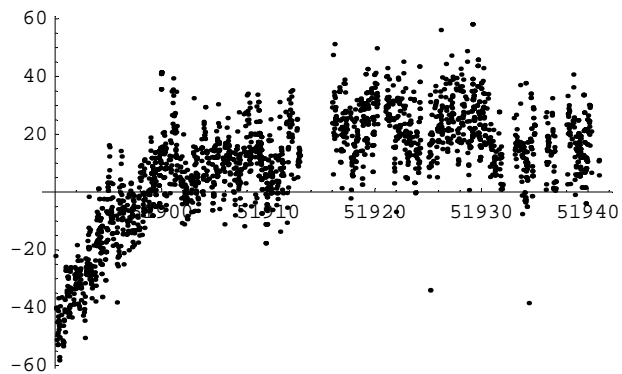
```
In[114]:= Off[General::spell1];  
In[115]:= dataPath = "g:\\Trip 2\\NML Jan 2001\\";
```

■ Definitions

```
In[138]:= dataHost = ReadCCTF["host.cctf"];  
(*Host reported values:*)  
RepHostIntDly = 50;  
  RepHostRefDly = 79;  
  RepHostAntDly = 235;  
RepHostDly = RepHostIntDly + RepHostAntDly - RepHostRefDly;  
  
(*Host Receiver internal settings:*)  
RxHostIntDly = 68;  
  RxHostRefDly = 79;  
  RxHostAntDly = 235;  
RxHostDly = RxHostIntDly + RxHostAntDly - RxHostRefDly;  
HostCorrection = RepHostDly - RxHostDly;  
  
dataTrav = ReadCCTF["trav.cctf"];  
(*Host reported values:*)  
RepTravIntDly = 68;  
  RepTravRefDly = 77.8;  
  RepTravAntDly = 235;  
RepTravDly = RepTravIntDly + RepTravAntDly - RepTravRefDly;  
  
(*Travelling receiver internal settings:*)  
RxTravIntDly = 68;  
  RxTravRefDly = 77.8;  
  RxTravAntDly = 235;  
RxTravDly = RxTravIntDly + RxTravAntDly - RxTravRefDly;  
TravCorrection = RepTravDly - RxTravDly;  
Null  
  
> Read 3322 tracks from g:\Trip 2\NML Jan 2001\host.cctf  
> Read 2279 tracks from g:\Trip 2\NML Jan 2001\trav.cctf  
  
In[159]:= << Graphics`Graphics`
```

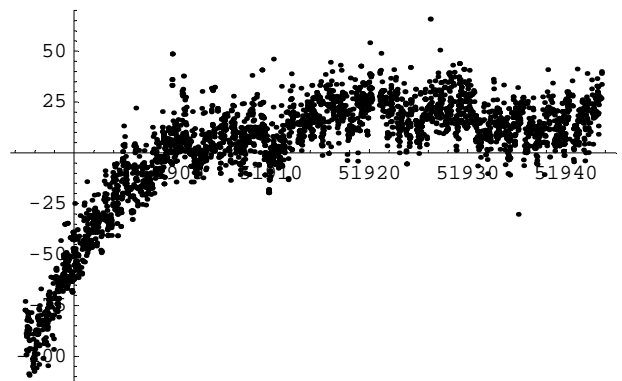
```
In[160]:= ListPlot[MakeXY[Map[DateValue, dataTrav], Map[RefGPS, dataTrav]],
  PlotRange -> All];
```

(* RAW DATA FROM TRAVELLING RECEIVER *)



```
In[161]:= ListPlot[MakeXY[Map[DateValue, dataHost], Map[RefGPS, dataHost]],
  PlotRange -> All];
```

(* RAW DATA FROM NPL HOST *)



```
In[162]:= dMerge = MergeCCTF[dataHost, dataTrav];
```

> First 3322 tracks, second 2279 tracks, matching 1538 tracks

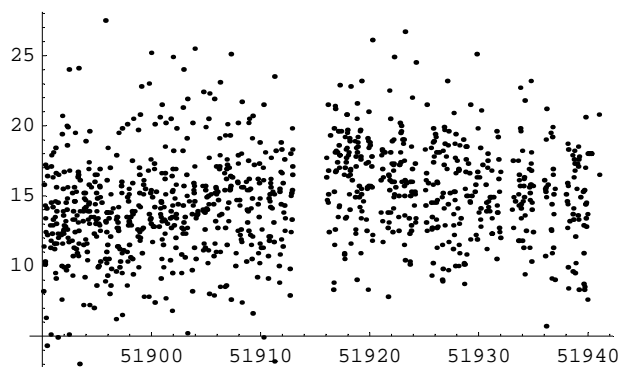
```
In[163]:= diffdataGPS =
  Map[{DateValue[#1], RefSV[#1] - RefSV2[#1] - HostCorrection + TravCorrection,
    TrackLength[#1], TrackLength2[#1]} &, dMerge];
```

```
In[164]:= diffdataGPS = FilterTrackLength[diffdataGPS, 780];
```

1338 common tracks out of 1538 were of length greater than or equal to 780 seconds.

```
In[165]:= ListPlot[diffdataGPS, PlotRange -> All];
```

```
(* HOST RECEIVER DATA - TRAVELLING RECEIVER DATA *)
```



```
In[166]:= << Statistics`LinearRegression`
```

```
In[167]:= regress = Regress[diffdataGPS, {1, x}, x];
rtable = ANOVATable /. regress;
ptable = ParameterTable /. regress;
MJDFirst = First[dMerge][[3]];
MJDLast = Last[dMerge][[3]];
MJDMiddle = MJDFirst + (MJDFirst - MJDLast) / 2;
intercept = ptable[[1, 1, 1]];
SEintercept = ptable[[1, 1, 2]];
slope = ptable[[1, 2, 1]];
SEslope = ptable[[1, 2, 2]];
rms = Sqrt[rtable[[1, 2, 3]]];
MeanOffset = intercept + slope * MJDMiddle;
Print["!\(\(*
StyleBox[\"Summary\", \n\"Output\"]\");
Print[Length[dMerge], " common-view tracks were analysed between MJD ",
MJDFirst, " and MJD ", MJDLast];
Print["The mean offset (Host Rx - Travelling Rx) between the two receivers was ",
MeanOffset, " ns, with an RMS deviation of ", rms, " ns.];
Print["The slope of the line of best fit was ", slope*1000,
" ps/day, with a standard error of ", SEslope*1000, " ps/day.];
```

Summary

1538 common-view tracks were analysed between MJD 51890 and MJD 51941

The mean offset (Host Rx - Travelling Rx) between the two receivers was
12.9816 ns, with an RMS deviation of 3.52207 ns.

The slope of the line of best fit was
36.9432 ps/day, with a standard error of 6.30229 ps/day.