

## ■ Processing APMP\_Cal data from VMI Vietnam

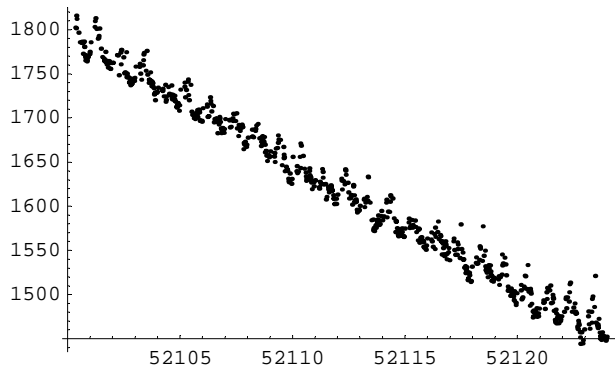
```
Off[General::spell1];  
  
dataPath = "f:\\Trip 2\\VMI Vietnam\\";
```

### ■ Definitions

```
dataHost = ReadCCTF["host.txt"];  
(*Host reported values:*)  
RepHostIntDly = 50;  
  RepHostRefDly = 38;  
  RepHostAntDly = 250;  
RepHostDly = RepHostIntDly + RepHostAntDly - RepHostRefDly;  
  
(*Host Receiver internal settings:*)  
RxHostIntDly = 50;  
  RxHostRefDly = 23;  
  RxHostAntDly = 250;  
RxHostDly = RxHostIntDly + RxHostAntDly - RxHostRefDly;  
HostCorrection = RepHostDly - RxHostDly;  
  
dataTrav = ReadCCTF["trav.txt"];  
(*Host reported values:*)  
RepTravIntDly = 68;  
  RepTravRefDly = 61;  
  RepTravAntDly = 234.5;  
RepTravDly = RepTravIntDly + RepTravAntDly - RepTravRefDly;  
  
(*Travelling receiver internal settings:*)  
RxTravIntDly = 68;  
  RxTravRefDly = 68;  
  RxTravAntDly = 235;  
RxTravDly = RxTravIntDly + RxTravAntDly - RxTravRefDly;  
TravCorrection = RepTravDly - RxTravDly;  
Null  
  
> Read 742 tracks from f:\Trip 2\VMI Vietnam\host.txt  
> Read 709 tracks from f:\Trip 2\VMI Vietnam\trav.txt  
  
<< Graphics`Graphics`
```

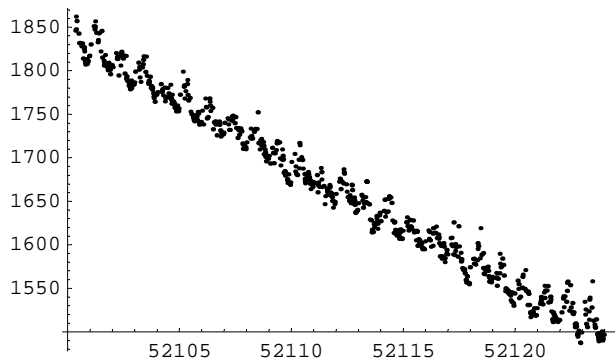
```
ListPlot[MakeXY[Map[DateValue, dataTrav], Map[RefGPS, dataTrav]],
  PlotRange -> All];
```

(\* RAW DATA FROM TRAVELLING RECEIVER \*)



```
ListPlot[MakeXY[Map[DateValue, dataHost], Map[RefGPS, dataHost]],
  PlotRange -> All];
```

(\* RAW DATA FROM VMI HOST \*)



```
dMerge = MergeCCTF[dataHost, dataTrav];
```

```
> First 742 tracks, second 709 tracks, matching 657 tracks
```

```
diffdataGPS =
```

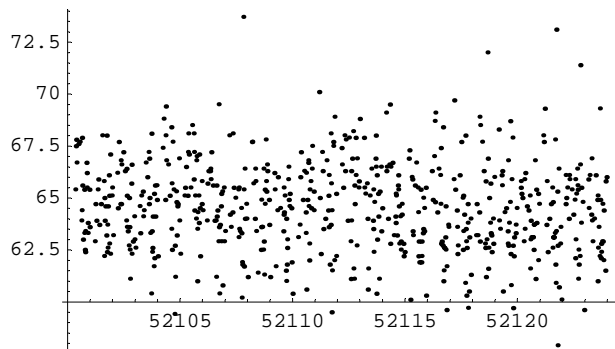
```
  Map[{DateValue[#1], RefSV[#1] - RefSV2[#1] - HostCorrection + TravCorrection,
    TrackLength[#1], TrackLength2[#1]} &, dMerge];
```

```
diffdataGPS = FilterTrackLength[diffdataGPS, 780];
```

```
629 common tracks out of 657 were of length greater than or equal to 780 seconds.
```

```
ListPlot[diffdataGPS, PlotRange -> All];
```

```
(* HOST RECEIVER DATA - TRAVELLING RECEIVER DATA *)
```



```
<< Statistics`LinearRegression`
```

```
regress = Regress[diffdataGPS, {1, x}, x];
rtable = ANOVATable /. regress;
ptable = ParameterTable /. regress;
MJDFirst = First[dMerge][[3]];
MJDLast = Last[dMerge][[3]];
MJDMiddle = MJDFirst + (MJDFirst - MJDLast) / 2;
intercept = ptable[[1, 1, 1]];
SEintercept = ptable[[1, 1, 2]];
slope = ptable[[1, 2, 1]];
SEslope = ptable[[1, 2, 2]];
rms = Sqrt[rtable[[1, 2, 3]]];
MeanOffset = intercept + slope * MJDMiddle;
Print["!\(\(*
StyleBox[\"Summary\", \n\"Output\"]\)\);
Print[Length[dMerge], \" common-view tracks were analysed between MJD \",
  MJDFirst, \" and MJD \", MJDLast];
Print[\"The mean offset (Host Rx - Travelling Rx) between the two receivers was \",
  MeanOffset, \" ns, with an RMS deviation of \", rms, \" ns.\"];
Print[\"The slope of the line of best fit was \", slope*1000,
  \" ps/day, with a standard error of \", SESlope*1000, \" ps/day.\"];
```

```
Summary
```

```
657 common-view tracks were analysed between MJD 52100 and MJD 52123
```

```
The mean offset (Host Rx - Travelling Rx) between the two receivers was
65.3529 ns, with an RMS deviation of 2.14309 ns.
```

```
The slope of the line of best fit was
-33.3683 ps/day, with a standard error of 12.3362 ps/day.
```